1. User toggles RC (Jetson server) connection
2. Client system initializes server connection
   1. ClientManager signals NetworkManager to initialize the server connection
   2. NetworkManager signals ServerControlManager to begin the server connection
   3. ServerControlManager initializes the Jetson system application
3. Jetson ServerManager initializes the server system
   1. Jetson initializes the SensorMonitor
      1. SensorMonitor begins pulling from the sensor pins
      2. SensorMonitor constructs and populates SensorState object
   2. Jetson initializes the CameraManager
      1. CameraManager creates two CaptureControllers
      2. CaptureControllers initialize their capture program
      3. CameraManager is prepared for use
   3. Jetson initializes the RTSPManager
      1. RTSPManager initializes Live555 library methods
      2. RTSPManager is prepared to broadcast
   4. Jetson initializes the RCManager
      1. RCManager initializes the ServoController
      2. ServoController sets to zero position
      3. RCManager initializes the MotorController
      4. MotorController sets to zero position
   5. Jetson begins receiving the controller stream
4. Jetson notifies Client system of successful initialization
5. Client System notifies user of Server connection